

Michael Goodrich

Michael A. Goodrich is a professor in the Computer Science Department at Brigham Young University. He joined the Computer Science faculty at Brigham Young University in 1998 after completing a post-doctoral research position at Nissan Cambridge Basic Research in Cambridge, Massachusetts from 1996-1998. He received his Ph.D. in Electrical and Computer Engineering from Brigham Young University in 1996. From January 2004 through August 2009, he was the steering committee co-chair for the ACM/IEEE RAS International Conference on Human-Robot Interaction, and he chaired the inaugural meeting of that conference in 2006. His research interests include human-robot interaction, which includes designing and evaluating interfaces for ground and aerial robots, and artificial intelligence, which includes designing multi-agent learning algorithms. His current funded research projects include using mini-UAVs to support wilderness search and rescue, designing user interfaces to allow therapists to control robots that assist children with autism, and extending the limits of how many robots a team of humans can effectively manage.