UCAR





Unmanned Combat Armed Rotorcraft

Human Machine Interaction Concepts for the Unmanned Combat Armed Rotorcraft (UCAR)

Tom Spura, Lockheed Martin Corp. Chris Miller, SIFT Inc.

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LOCKHEED MARTIN















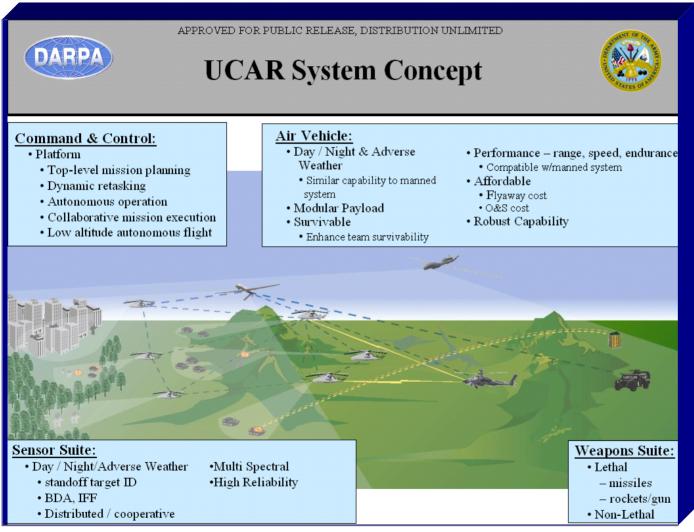
Agenda



- UCAR Overview
- UCAR Video
- HMI Design Challenges
- Options for HMI Solutions
- Questions and Answers

DARPA System Concept





Command and Control from Air or Ground

Non-expendable, Lethal VTOL using heavy fuel

Global deployment, use with Army initial entry force

System integrity consistent with use over populated areas

System Ao > 90%

DARPA Goals and Objectives





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UCAR Goals & Objectives



Demonstrate the capability to affordably and effectively identify and prosecute masked ground targets at ranges that limit threat capability to engage friendly forces

- Develop Key Technologies
 - Key technologies to enable the next generation of autonomous & collaborative operations, enhanced survivability at altitudes above nap-of-theearth, low-altitude autonomous flight, and standoff target identification

Technologies that are broadly applicable to Objective Force manned and unmanned aviation systems

- Demonstrate
 - The capabilities represented by the key technologies in a UCAR demonstration system in FY06 (Phase III)
- Mature
 - If the capability offered by UCAR is compelling
 - · Demonstrate the capability to perform armed reconnaissance, attack, and other core aviation missions in an Objective Force system-of-systems environment
 - · Mature the UCAR system capability to a level that is suitable for entry into SDD

Develop Technologies for autonomous rotorcraft

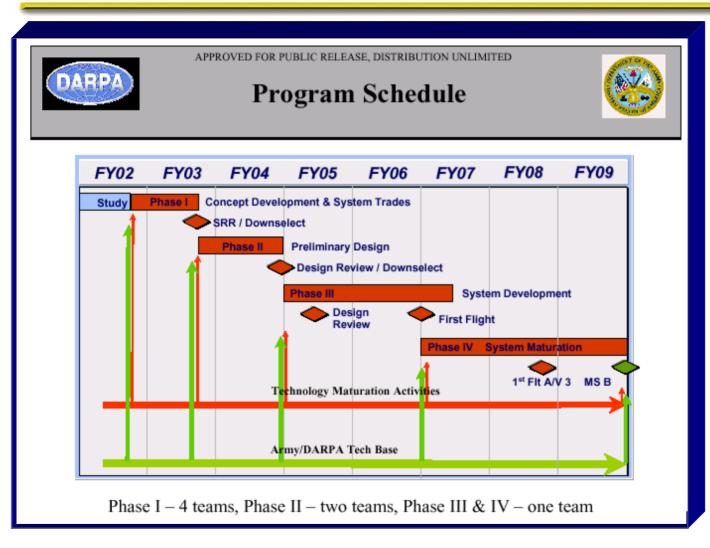
Investigate armed unmanned capabilities to support warfighter

Demonstrate and mature technologies through series of demonstrations

Position program concepts for transition to use

DARPA Program Schedule





Phase 1:

4 Contractors **Initial Concepts and System Trades**

Phase 2:

2 Contractors **Preliminary Design** of Demonstrator

Phase 3 and 4:

1 Contractor Series of Risk Reduction **Demonstrations and Design Maturation**

UCAR – Transformational Program





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Unmanned Combat Armed Rotorcraft - A Transformational System -



UNMANNED / MANNED INTEGRATION

- Cooperative mission execution to exploit the strengths of all systems
- Reduces risk to manned platforms
- Relieves manned platforms of the need to perform the dull, dirty, and dangerous missions

AUTONOMOUS

- Advances in state-of-the art
 - · Mission planning & execution
 - · Collaboration among platforms

SURVIVABLE

Advances in state-of-the-art to enhance survivability at low altitude

LETHAL

- Able to ID targets at long range
- Immediate prosecution of time-sensitive targets

AFFORDABLE

Reduced acquisition, training, and support cost

<u>UCAR –</u> <u>Transformational</u> <u>Program:</u>

Provide Army with unmanned rotorcraft to support Future Force

Force multiplier for warfighter

Position for transition to Army program in 2009

The LM Team Vision ...

"The Wolves of War"



Our UCAR Objective System is Envisioned to be a Ferocious Pack of Relentless, Cunning, Intelligent, Lean, Staunch, Deadly Wolves – Efficient in Their Missions and Responsive to the Warfighter's Intentions

- <u>Relentless</u> Persistent in the pursuit of their goals ... Built to do the 'Dull, Dirty and Dangerous' missions
- <u>Cunning</u> Intelligent use of tactics, techniques, and procedures ... Sly use of multi-spectral survivability and LPI/LPD sensors and communications
- <u>Intelligent</u> Agile 3-D quickness at low altitudes ... Battlespace reasoning ... and mission re-planning on the run
- <u>Lean</u> Affordable, durable, economical ... Horizontally-integrated into the DoD's support structure ... Low personnel and training burdens
- <u>Staunch</u> Trusted and dependable performance ... Behavior is expected and understood
- <u>Deadly</u> Employs all weapons available, both on-board and off-board ...
 Matched to the targets with awesome precision

LM UCAR Video





Lockheed Martin UCAR Public Release Video – 9 min.

HMI Design Challenges



UCAR objectives drive design to allow multiple UCAR vehicles to be controlled by single operator.

Operators are already engrossed in high workload environments.

Workload issues –

- C2 of multiple vehicles by single operator
- Managing workload to allow for C2 of vehicles

Context tracking –

- Maintaining awareness of UCAR vehicles as well as ownship situations.
- Operator switching between situations, and returning to original tasks

System trust -

- Introducing new operational concepts to warfighter
- Incorporating autonomy that is effective, predictable and controllable

Options for HMI Solutions



Phase 1 of UCAR Program conducted Trade Studies looking at options for System Designs

Human Machine Interface one of critical areas reviewed. Results of Trades still Competition Sensitive. Some key attributes listed here:

Channels of Interaction –

- Think outside the standard interface routes, are there other ways to get information to operator, within constraints of environment.
- Integrate as much as possible with current C2 systems
- Develop a modular architecture that can be ported to multiple host platforms

Work with automation, do not rely on it —

- Automation provides reduced workload, but adds new challenges
- Must work with engineers providing automation to insure user needs are met

Test Concept with Operators, demonstrate to customers –

- First concepts need to adapt to evolving requirements
- Be adaptable everything can change!





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